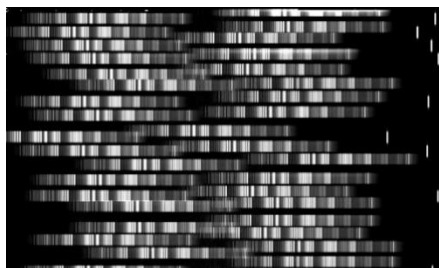


# DMD-Based Multi-Object Spectrograph Design and Wavelength Calibration

## 1. INTRODUCTION

A multi-object spectrograph (MOS) is an instrument that can acquire the spectra of hundreds of astrophysical objects simultaneously, saving much on observing time. In the recent years, the **digital micromirror device (DMD)** has shown potential in becoming the central component of the MOS, being used as a programmable slit mask [1]. We have designed a seeing-limited DMD-based MOS covering a spectral range of **0.4-0.7  $\mu\text{m}$** , with a field of view (FOV) of **19.20'  $\times$  25.60'** and a spectral resolution of **1000**. We present the optical design of this DMD-MOS and a wavelength calibration procedure for hyperspectral data reduction.



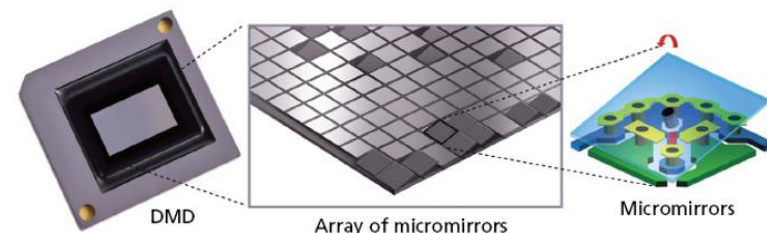
**Figure 1** - Example of multi-object spectra from the Gemini Multi-Object Spectrograph (GMOS) (Original Image: Gemini Observatory)

## 2. DMD ADVANTAGES

Current MOS systems mainly use two different types of object selection systems:

1. Repositionable optical fibres (e.g. Subaru FMOS [2]), which take time to configure [3]
2. Custom-made slit masks (e.g. Gemini GMOS [4]), which are made ad hoc with high costs

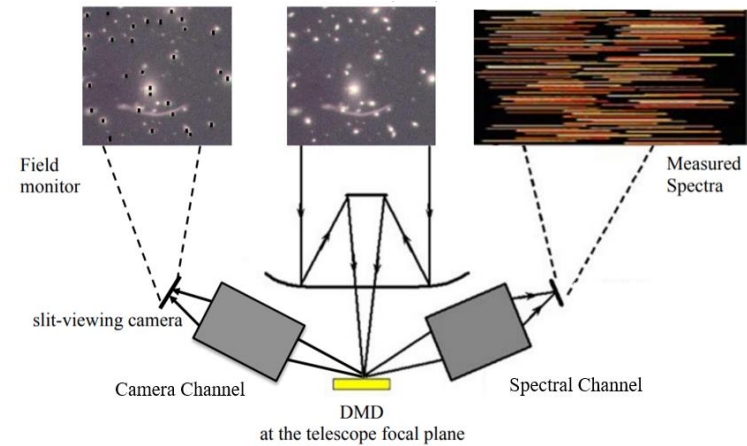
A DMD can be used as a **generalizable slit mask** that can be quickly programmed. A DMD consists of an array of many tiny mirrors (13.70  $\mu\text{m}$  pitch each), which can be individually programmed to tilt along an axis,  $\pm 12^\circ$ , corresponding to an ON and an OFF configuration. DMDs have been used for commercial and industrial applications, and thus have **lower costs** and **proven reliability**.



**Figure 2** - Digital Micromirror Device (Original Image: LEDs Magazine)

### 3. DMD-MOS SYSTEM OVERVIEW

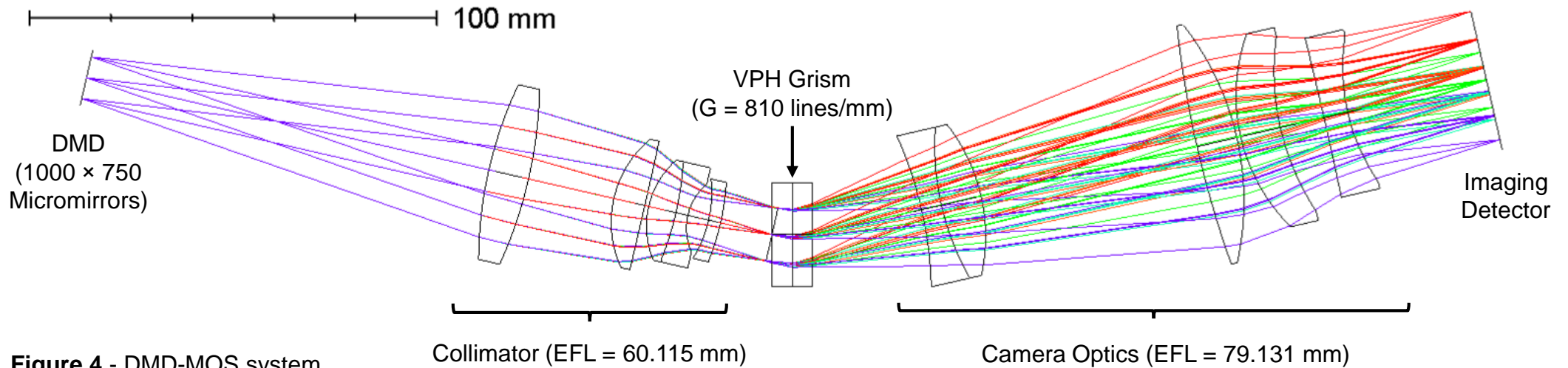
Incoming light from a telescope is focused onto the plane of the DMD. Micromirrors in the ON configuration act like slits in a conventional spectrograph, reflecting incoming light into a **spectral channel** to acquire the spectra of objects. Micromirrors in the OFF configuration reflect incoming light into a **camera channel** for standard imaging and object selection (fields acquisition). Since the camera channel is just a conventional imaging system, our research focus is on the spectral channel.



**Figure 3 -** DMD-MOS system layout (Original Image: Roberto et al., 2016 [5])

### 4. OPTICAL DESIGN

Our DMD-MOS employs **all-spherical refractive optics**. Light reflected by the micromirrors into the spectral channel pass through a collimator, and then is dispersed by a **volume phase holographic (VPH) grism**. The dispersed light is then focused by some camera optics onto an imaging detector.

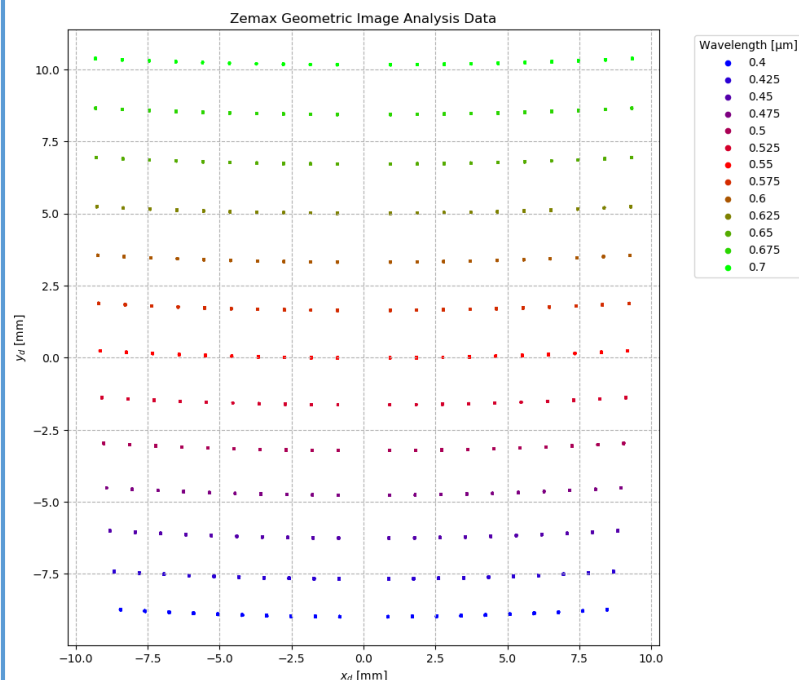


**Figure 4 -** DMD-MOS system diagram for the spectral channel, from DMD to image plane (detector)

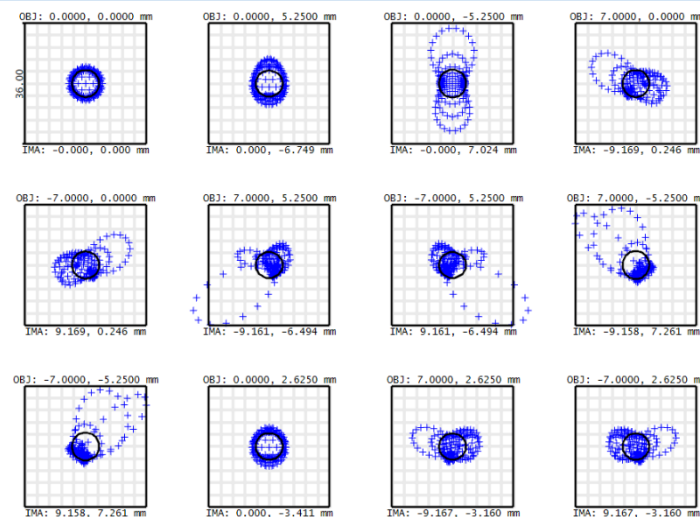
## 5. OPTICAL PERFORMANCE

An analysis of the system was conducted, and the DMD-MOS meets the design requirements:

- RMS Spot Radii are less than  $2\times$  the pitch of a pixel ( $9\ \mu\text{m}$ ) (by Nyquist Theorem)
- Spectral resolution of the system  $>1000$
- All rays within the FOV and with wavelength  $0.4\text{-}0.7\ \mu\text{m}$  will fall on detector; no rays clipped



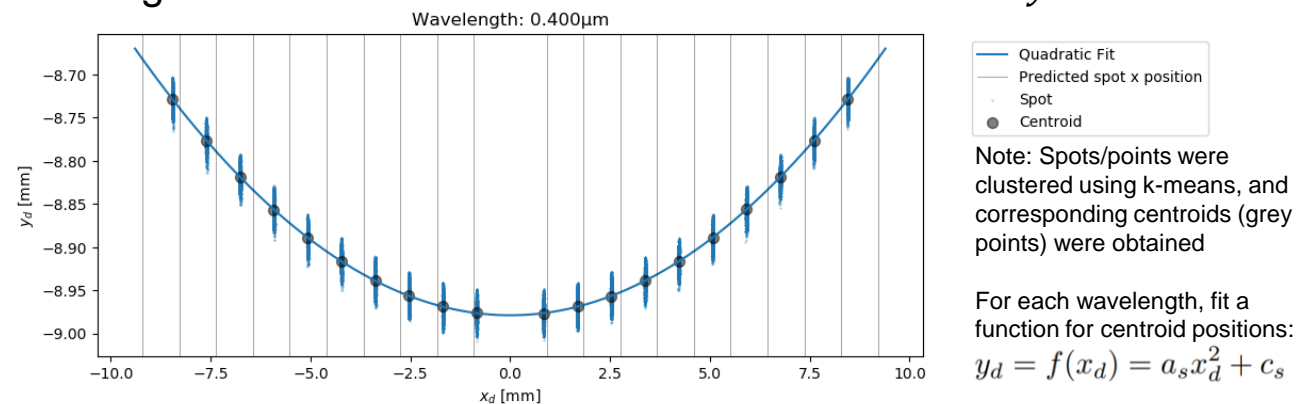
**Figure 6** - Diagram of where rays land (spots/points) on the image plane, obtained by **launching 1 million rays** into the system, with the DMD having 20 ON micromirrors along its centreline; 13 different wavelengths were used for this Monte Carlo style simulation in Zemax OpticStudio (optical design software)



**Figure 5** - Spot Diagrams of the DMD-MOS system, which can be used to determine RMS spot radius and optical performance; rays are from a variety of field positions on the DMD as indicated above each diagram, and are at centre wavelength  $\lambda_c = 0.55\ \mu\text{m}$ ; the black ring in each diagram is the airy disk

## 6. WAVELENGTH CALIBRATION FIT

Hyperspectral imaging systems have **smile distortion** and **keystone distortion** which need to be corrected. A wavelength fit was determined for this DMD-MOS system to map points from the DMD plane,  $(x, y)$ , to corresponding points on the image plane (detector),  $(x_d, y_d)$ , for some wavelength  $\lambda$ , using **simulated data** from Figure 6 in which DMD ON micromirrors were at  $y = 0$ .



**Figure 7** - Smile distortion at minimum wavelength  $\lambda = 0.40\ \mu\text{m}$ , where distortion is greatest; note that smile distortion can be fitted with a **quadratic function**, with coefficients  $a_s$  and  $c_s$  that depend on  $\lambda$

Note: Spots/points were clustered using k-means, and corresponding centroids (grey points) were obtained

For each wavelength, fit a function for centroid positions:  
 $y_d = f(x_d) = a_s x_d^2 + c_s$

## 6. WAVELENGTH CALIBRATION FIT (Continued)

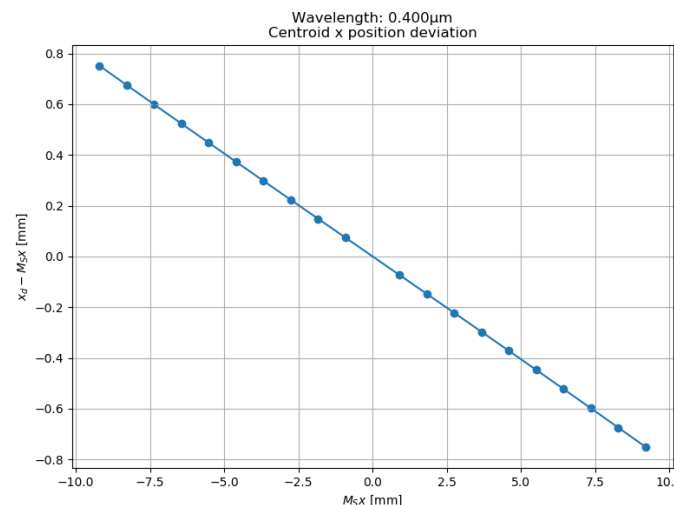
The **k-means clustering** algorithm was used to cluster points together corresponding to rays from the same micromirror. Given some point  $(x, y)$  with  $y = 0$ ,  $\lambda$ , and the magnification of the spectrograph  $M_S$ :  $x_d$  and  $y_d$  can be found with the equations and constants below, with a **maximum error of 0.022 mm** at  $\lambda = 0.40 \mu\text{m}$ . Note that  $x$  and  $y$  are in units of mm and  $\lambda$  is in units of  $\mu\text{m}$ .

$$x_d = \left( \sum_{i=0}^2 a_{ki} \lambda^i \right) (M_S x)^3 + \left( \left[ \sum_{i=0}^3 c_{ki} \lambda^i \right] + 1 \right) (M_S x)$$

$$y_d = \left( \sum_{i=0}^3 a_{si} \lambda^i \right) \left[ \left( \sum_{i=0}^2 a_{ki} \lambda^i \right) (M_S x)^3 + \left( \left[ \sum_{i=0}^3 c_{ki} \lambda^i \right] + 1 \right) (M_S x) \right]^2 + \sum_{i=0}^3 c_{si} \lambda^i$$

Distortion Type	Constant	Value	Distortion Type	Constant	Value
Smile	$a_{s0}$	0.00782671	Keystone	$a_{k0}$	0.00007896
	$a_{s1}$	-0.01890454		$a_{k1}$	-0.00030339
	$a_{s2}$	0.02581286		$a_{k2}$	0.00019631
	$a_{s3}$	-0.01394186		$c_{k0}$	-1.23198145
	$c_{s0}$	-14.86248407		$c_{k1}$	5.53880362
	$c_{s1}$	-35.79126845		$c_{k2}$	-8.34571333
	$c_{s2}$	158.05186215		$c_{k3}$	4.25929110
	$c_{s3}$	-79.78971198			

**Table 1** - Values of various constants in the above fit equations



For each wavelength, find a fit for the centroid "deviation":

$$g(x) \equiv x_d - (M_S x)$$

$$g(x) = a_k (M_S x)^3 + c_k (M_S x)$$

**Figure 8** - Keystone distortion at minimum wavelength  $\lambda = 0.40 \mu\text{m}$ , where distortion is greatest; note that keystone distortion can be fitted with a **cubic function**, with coefficients  $a_k$  and  $c_k$  that depend on  $\lambda$

## 7. CONCLUSION AND NEXT STEPS

We completed the optical design of this DMD-MOS and verified its performance with design constraints. A wavelength fit was determined for the case of  $y = 0$ , which we will generalize to the entire FOV ( $y \neq 0$ ) next. A larger number of rays will be used for future simulations to reduce the error of the fit. After a generalized fit is determined, we hope to extend this fit procedure and DMD-MOS instrument to other applications, such as remote sensing. This DMD-MOS will be placed on a 16 inch telescope at the University of Toronto, and will be used as an exploratory study for future DMD-based MOS systems.

## 8. REFERENCES

- [1] M. Robberto et al., "Applications of DMDs for astrophysical research," *Proc. SPIE* 7210, Emerging Digital Micromirror Device Based Systems and Applications, 72100A (13 February 2009).
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- [4] R. L. Davies et al., "GMOS: the GEMINI Multiple Object Spectrographs," *Proc. SPIE* 2871, Optical Telescopes of Today and Tomorrow (21 March 1997).
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